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# Department of Electronics and Communication Engineering Program: B. Tech -ECE

Academic Year: 2023-24

COURSE CODE	COURSE TITLE	CO NO	DESCRIPTION OF COURSE OUTCOME
		1	Analyze the human bio-electric and Nonelectrical signal characteristics and understand the functionality of each body parts.
		2	Apply the Knowledge of Medical Instruments in clinical and ambulance to assist
23EC2228F	Biomedical Electronics & IOT for Healthcare	3	Apply the knowledge of various Bio-sensors for healthcare using Nextgen Internet of Things Technology.
		4	Analyze the various applications of IoMT in real world.
		5	Design the IoT based Health monitoring and Elderly Assist modules.
	Electronic Circuits for Medical Instrumentation	1	Identifying sources of bioelectric phenomena in nerves, muscles and examine the general properties of physiological systems, including nonlinearity and non-stationarity.
		2	Demonstrate amplifiers and find random noise related factors which is to be useful measures of a signal conditioning systems.
23EC2236F		3	Interpret aliasing and the sampling theorem, Analog-to-digital and digital-to-analog converters.
		4	Illustrate several circuits and systems applied in medical instrumentation.
		5	Experimental design, simulate and analyze bio signal characteristics using MATLAB/Multisim/COMSOL.
		1	Demonstrate the basic concepts related to Biomedical signals and images.
		2	Classify the Bio medical signal processing methods to eliminate the artefacts arise in biomedical signals.
22BMI3101 R	Biomedical Signal and	3	Explain the Biomedical imaging and enhancement techniques.
K	image i rocessing	4	Apply advanced signal processing approaches for biomedical signals and images.
		5	Analyze and implement appropriate signal/Image processing algorithms for practical problems involving biomedical signals and systems Using MATLAB.



		6	Case Study of the Bio medical Audio signal Analysis and Biomedical Image Analysis
			Summarize the basic concepts of digital signal
		1	processing techniques and identify the nature of
			Biomedical signals.
	Advanced Biomedical	2	Apply the Filtering Techniques.
22BMI3202	Signal and Image	-	Analyze the various Techniques for Detection of
	Processing	3	Events and Biosignals.
		1	Analyze several circuits and systems for the
		4	application in medical instrumentation.
		1	Summarize the characteristics of biomaterials.
		2	Apply surface modification for biomedical
			applications.
		3	Apply Biocompatibility Testing and Response of
		5	Biomaterial to Human Body.
22BMI3303	Materials for Bio-Medical	Δ	Analyse Bio-implants & Surgical Aids for
R	Applications	-	biomedical applications.
R	rippiloutions		Design and evaluate a solution based on
		5	nanomaterial technology for a given need in the
		5	field of healthcare and biomedical Engineering
			using COMSOL/OFDTD.
		6	Evaluating and identify suitable biomaterials for
		Ŭ	biosensors
		1	Summarize the basic concepts of Nanosensors
		2	Interpret the fabrication, characterization of
22BMI3404	Nanotechnology and	_	nanosensors
	Nanosensors	3	Apply nanomaterials to manipulate nanosensors
		4	Apply quantum dots in Sensing and Imaging
			Application.
		1	Summarize the working principles of biosensors
		2	Interpret characterization of optical and
			electrochemical sensors
2201 (12505	Biosensing and	3	Apply the response of biosensors
22BMI3505	Bioelectronics	4	Analyse selective biomedical devices for future
			applications
		~	Design and interfacing of Biological Systems with
		5	electronic systems, non-conventional bioelectronic
			devices using SPICE/OFD1D/COMSOL
		1	Apply the knowledge of communication to
23EC2210R		1	detalink lover
	Natural Protocols and	2	Analyza various MAC protocols and apply IP
	INETWORK Protocols and		addressing concents to subnet a network
	Security		Analyse static and dynamic routing algorithms and
		3	transport layer protocols
		Δ	Analyse application layer protocols and various
		т	r mary se appreadon ray or protocors and various



			cryptographic algorithms
			Analyse the functionality of the network using
		5	different protocols and working of various
			cryptographic algorithms.
			Apply the knowledge of communication to
		1	understand the concepts of physical layer and
			datalink layer.
			Analyze various MAC protocols and apply IP
		2	addressing concepts to subnet a network.
		_	Analyze static and dynamic routing algorithms
	Network Protocols and	3	and transport layer protocols.
23EC2210A	Security		Analyze application layer protocols and various
	Security	4	cryptographic algorithms
			Analyze various link layer protocols and advanced
		5	security concepts
			Analyze the functionality of the network using
		6	different protocols and working of various
		0	cryptographic algorithms
			Apply the knowledge of communication to
		1	understand the concepts of physical layer and
	Network Protocols and Security	1	datalink layer
			Analyze various MAC protocols and apply IP
		2	addressing concepts to subnet a network
			Analyze static and dynamic routing algorithms
		3	and transport layer protocols
23EC2210P			Analyze application layer protocols and various
		4	cryptographic algorithms
		5	Analyze various link layer protocols and advanced
			security concents
			Analyze the functionality of the network using
		6	different protocols and working of various
			cryptographic algorithms
		1	Interpret the basics of network threats and attacks
		1	Interpret network security Protocols and
		2	technologies such as SSL TLS and IP Security
		2	Architecture
			Interpret Network defense using Access control
23EC2235E	Resilient Networks	3	Password management Incident response security
252022551	Resilient Pretworks	5	awareness
			Analyze different Secure network architectures
		4	and Hardening
			Analyze the network security functions by
		5	configuring networks with the given requirements
			Apply the knowledge of networks to WI ANs and
		1	802 11 WI ANS and IP Networking
23EC2239F	Wireless LANS		Radio transmission canacity. Throughout
		2	Interpret Bandwidth afficiency Forward error
			Interpret Danuwium, erretency, rorword error



			correction
		3	Interpret WLAN switches and MAC Protocols
		4	Analyse IEEE8020.11 protocols and frame
		4	structure.
			Simulate and verify the connectivity of Access
		5	controller (AC) and Access points (AP) using
			eNSP simulator
			Apply the knowledge of networks understand the
		1	Architectural Evolution of TCP/IP, standards,
		1	Comparisons between OSI/ISO & ICP/IP
			ATM ADD and their analysis
			Analyse DHCP Theory and Operation DHCP
23CC3101R	TCP/IP & Other Protocol	2	Architecture DHCP Auto-Configuration:
250051011	Suites	2	Network Address Translation
		3	Analyse Domain Name system
			Analyse ICMPv4/v6, IGMP, MLD, UDP, IP
		4	Fragmentation, IP Sec, EAP
		~	Analyse and deployment different protocols suites
		5	using Cisco packet tracer
		1	Apply the knowledge of networks understand the
			Architectural Evolution of TCP/IP, standards,
			Comparisons between OSI/ISO & TCP/IP
			Protocol Suite, different Addressing systems,
			ATM ARP and their analysis
		2	Analyze DHCP Theory and Operation, DHCP
			Architecture, DHCP Auto-Configuration:
220021014	TCP/IP & Other Protocol Suites	2	Network Address Translation
23CC3101A		3	Analyze Domain Name system
		4	Fragmontation ID Sec. EAD
			Analyze and deployment different protocols suites
		5	using Cisco packet tracer
			Simulate and analyze different protocols suites
		6	using Cisco packet tracer
		-	Simulate and analyze the advanced features of
		/	protocol suites
		1	Apply the concepts of Cloud computing in
		1	Networking
		2	Able to analyse different Topologies and
22002102	Cloud Computing and	2	Architecture standards
23003102	Networks Security	3	Apply security concepts in could computing
		4	Analysis of various Network Security issues
		5	Inspect the privacy and security, architecture,
		5	design in Edge computing



23CC3203R	VoIP Systems & Broadband Networks – VoIP	1	Apply the basic concepts of Classical Telephony, IP Networking and SS7 signaling
		2	Analyze different VoIP Architectures and Protocols
		3	Analyze Broadband Wireless, Access Technologies, Passive Optical Networks and Fiber-to-the-Home in real time scenario
		4	Analyze Broadband Optical NWs and Multimedia Network-Connection
		5	Analysis of VoIP Protocols using Cisco packet tracer
		1	Apply the basic concepts of Classical Telephony, IP Networking and SS7 signaling
		2	Analyze different VoIP Architectures and Protocols
		3	Analyze Broadband Wireless, Access Technologies, Passive Optical Networks and
23CC3203A	VoIP Systems & Broadband Networks – VoIP	4	Fiber-to-the-Home in real time scenario Analyze Broadband Optical NWs and Multimedia
		•	Network-Connection
		5	VoIP protocol and apply the advanced boradband
		6	Analysis of VoIP Protocols using cisco packet tracer
		7	Analysis of VoIP Protocols using Wireshark
	5G Mobile and IEEE standards – 5GMS	1	Apply the concept of 5G & RF Front-End, advancement over LTE Beyond 4G, building Blocks of 5G, 5G Architecture, 5G for IoT Apps in modern communication issues.
22662404		2	Apply the principles of advanced waveforms and air interfaces, 5G Waveforms, Channels, Milli- meter wave technology, 5G Radio Access Technologies.
23003404		3	Apply 5G Evaluation & Applications: MTC, D2D Communication, Multi-hop D2D, multi-carrier D2D
		4	Appy IEEE802Std: 802.11 (WiFi), 802.15.1 (Bluetooth), 802.15.4 (Zigbee), 802.16 (WiMax), 4G/5G
		5	Implementation of call procedures used in 5G networks in 5G lab.
	IP Multimedia Subsystems	1	Interpret Next-Gen NWs, IMS Standards, Models, IMS Architectures and IMS Core NW
23CC3205	and Emerging Technologies IMS	2	Interpret IMS Protocol Stacks & IMS Operation: H248, MEGACO, RTP, RTCP, IMS to IMS Call/Flow Operation



		3	Interpret IMS-PSTN, IMS Services: Comparison of GSM, IMS, PSTN, Web-Msg, Voice Video, VoLTE, RCS
		4	Inspect Emerging Tech. of IMS & Appn: Cloud, IoT Applications, NFV, SDN, PDAS, DSL, Cable- Set-Top Box
		5	Inspect the knowledge of IP Multimedia Subsystems and Emerging Technologies to solve real world problems
		1	Apply the knowledge of Communication networks and wireless technologies to realize Wireless Adhoc Networks
OEEC0001	Wireless Ad-hoc Networks	2	Apply the concepts of different routing protocols in real scenarios.
		3	Analyze the concepts of MAC, transport layer and security protocols.
		4	Analyze the concepts of wireless sensor network and implementation of hardware architecture.
		1	Analyze and simulate Simple Topology Creation, TCP/IP Performance Analysis, Routing Protocols Evaluation, Traffic Modelling, Quality of Service (QoS) Analysis, Using NS-3
22SDEC04	Design of Networks using NS-3	2	Analyze and simulate Congestion Control Algorithms, Network Security Analysis, Network Protocol Development, Wireless Network Simulation, Peer-to-Peer (P2P) Networks, MPLS, IoT, SDN Using NS-3
		3	Analyze and simulate Wireless Network Simulation, Peer-to-Peer (P2P) Networks, MPLS, IoT, SDN Using NS-3
		1	Interpret the basics of network threats and attacks in Security monitoring and incident response
		2	Analyse cryptography algorithms and HMAC & CMAC: SHA -1 Algorithm.
22CCF3506	IT Security: Défense against digital dark arts	3	Analyse different Network authentication Protocols
		4	Analyse Network security Protocols and technologies
		5	Analyse the network security protocols and cryptography algorithms
		1	Demonstrate the client - server networks and their dynamics
22EC2238	Peer-To-Peer Networks	2	Apply and practice the unstructured networks and their applications
		3	Apply the random walk techniques for peer-to- peer networks
		4	Analyze the structured networks and their



			applications
		5	Analyze the different peer to peer networks
		1	Understand the basic Continuous Time Signals
		1	and Systems
		2	Solve the frequency domain challenges and
23EC2103	Signals & Communication	2	applications to systems.
23202103	Systems	3	Interpret the principles of linear and angle
			modulation and demodulation techniques.
		4	Analyze the analog transmitters and receivers in
		-	the presence of noise
		1	Understand the basic Continuous Time Signals
			and Systems
		2	solve the frequency domain challenges and
			Interpret the principles of linear and angle
	Signals & Communication	3	modulation and demodulation techniques
22EC2103A	Systems		Analyze the analog transmitters and receivers in
	bystellis	4	the presence of noise
		~	Analyze real time accepts of time and frequency
		5	domain systems
		6	Analyze the signal conditioning and
		0	communication systems
	DIGITAL COMMUNICATIONS	1	Understand the pulse modulation techniques.
		2	Interpret the transmission through band limited
		2	signals.
		3	Analyze the Digital Transmission via Carrier
23EC2208			Modulation
		4	Analyze the Spread Spectrum Modulation
		5 6	Analyze the nonlinear equilizers and modulation
			BER errors due to channel.
			Analyze digital modulation techniques using
		1	Understand the pulse modulation techniques
		1	Interpret the transmission through band limited
		2	signals
			Analyze the Digital Transmission via Carrier
		3	Modulation
	DIGITAL	4	Analyze the Spread Spectrum Modulation
23EC2208A	COMMUNICATIONS	~	Analyze the nonlinear equilizers and modulation
		5	BER errors due to channel.
			Analyze digital modulation techniques using
		6	simulation tools
		7	Analyze the advanced digital schemes using SDR
			hardware via GNU Radio.
23EC2208D	DIGITAL	1	Understand the pulse modulation techniques.
2520222001	COMMUNICATIONS	2	Interpret the transmission through band limited



			signals.
		3	Analyze the Digital Transmission via Carrier
		3	Modulation
		4	Analyze the Spread Spectrum Modulation
		5	Analyze the nonlinear equilizers and modulation
		5	BER errors due to channel.
		6	Analyze digital modulation techniques using
		0	simulation tools
		7	Analyze the advanced digital schemes using SDR
		,	hardware via GNU Radio.
			Understand working of cellular mobile
		1	communication and methods to imrove channel
			capacity and reduce interference
		2	Explore and study different fading mechanisms in
			mobile communication
23EC2020	Wireless Communication	3	Apply the concepts of equalization and diversity
			techniques to mitigate fading in wireless channels
		4	Interpret the concepts of wireless Architecture
			and Standards
		6	Analyze Spectrum bands of wireless technologies,
			verification of different types of fading and study
			Explore different frequency bands used in wireless
		1	communication and study Propagation
			Mechanisms
			Analyze Mobile Radio channel characterization
		2	with focus on signal variations.
	Radio Wave Propagation	-	Interpret tropospheric effects and ionospheric
225 (2002)		3	effects on radio wave propogations
23EC3021			
		4	Analyze wave Propagations in Underwater by
			anaryzing acoustic waves.
			Analyza various Spectrum hands of wireless
		6	communication and study different types of fading
		0	with various communication protocols
			with various communication protocols
		1	Interpret the Spreading Sequences and Multiuser
		1	systems and systems for packet evolution
		2	Demonstrate the Multi carrier modulations using
23FC4051	4G Wireless Technologies		OFDM
	and Cellular	3	Extrapolate the MIMO systems and its eigenmode
	Communication		channels
		4	Analyse the Ultra-Wide Band technologies and
			challenges
		5	Determine the multicarrier systems and multi
		-	antenna systems



		6	Analyse LTE and OFDM transmission in deep radio
		7	Determine the LTE frames using in spectrum and learning deep ratio techniques
		1	Interpret the Spreading Sequences and Multiuser systems and systems for packet evolution
		2	Demonstrate the Multi carrier modulations using OFDM
		3	Extrapolate the MIMO systems and its eigenmode channels
23EC4051A	4G Wireless Technologies and Cellular	4	Analyse the Ultra-Wide Band technologies and challenges
	Communication	5	Determine the multicarrier systems and multi antenna systems
		6	Analyse LTE and OFDM transmission in deep radio
		7	Determine the LTE frames using inspectrum and learning deep ratio techniques
	Modern Satellite Communication Systems	1	Interpret the concepts of satellite orbits, orbital mechanics and frequency allocations to enable Earth space communications.
		2	Interpret the subsystems that enable control of orbit and attitude in satellites.
23EC4052		3	Analyze the atmospheric impairments and mitigation techniques to enable earth-space communication.
		4	Analyze satellites application in enabling the 5G ecosystem.
		5	
		6	Analyze the mission requirements and simulate complex ground, sea, air, and space platform analyses in an integrated environment.
		7	• • •
		1	Interpreting the 5G's architectural framework, quality of service, security, and call flow process as per 3GPP standards, and unlock the potential of its use cases, deployment, and operational scenarios.
23EC4053	5G Wireless Technologies	2	Interpret the Multi-RAT Dual Connectivity (MR- DC) architecture from the UE and RAN perspectives, MR-DC bearers and strategies for managing secondary RAN node mobility and key 5G protocols for effective communication and security in mobile networks.
		3	Apply channel sounding, transport channel processing, and physical layer control signalling to design a radio-interface architecture that enables



			wireless connectivity.
		4	Analyze Multi-Antenna Transmission and Beam Management scenarios for enabling channel
		5	Analyze the QoS requirements for enabling real time communications and private networks
		6	Analyze the 5G architecture and call process with 3GPP standards using 5G mobile network.
	7	Design and Analyze the QoS requirements with respective use-case scenario to enable information exchange between devices with hardware reealization.	
23EC4053A	5G Wireless Technologies	1	Interpreting the 5G's architectural framework, quality of service, security, and call flow process as per 3GPP standards, and unlock the potential of its use cases, deployment, and operational scenarios.
		2	Interpret the Multi-RAT Dual Connectivity (MR- DC) architecture from the UE and RAN perspectives, MR-DC bearers and strategies for managing secondary RAN node mobility and key 5G protocols for effective communication and security in mobile networks
		3	Apply channel sounding, transport channel processing, and physical layer control signalling to design a radio-interface architecture that enables wireless connectivity.
		4	Analyze Multi-Antenna Transmission and Beam Management scenarios for enabling channel capacity for high throughput communications.
		5	Analyze the QoS requirements for enabling real time communications and private networks.
		6	Analyze the 5G architecture and call process with 3GPP standards using 5G mobile network.
		7	Design and Analyze the QoS requirements with respective use-case scenario to enable information exchange between devices with hardware reealization.
23EC4054		1	Interpret the behavior of wireless optical channel and its scattering parameters.
	Optical Wireless	2	Apply various channel models for estimation of losses in optical wireless communication.
	communications	3	Analyze and interception of modulation techniques utilized in VLC.
		4	Analyze the application of optical source detectors



		5	Analyze the free space optical communications techniques.
		1	Interpret the behavior of wireless optical channel and its scattering parameters
		2	Apply various channel models for estimation of losses in optical wireless communication.
23EC4054A	Optical Wireless communications	3	Analyze and interception of modulation techniques utilized in VLC.
		4	Analyze the application of optical source detectors
		5	Analyze the free space optical communications techniques.
		1	Assess mobile network coverage and optimize capacity using machine and deep learning algorithms.
		2	Analyze techniques to optimize energy efficiency in mobile networks and automate them using Machine Learning.
22EC4055	Machine Learning for Wireless Communications	3	Analyze the Adaptive Modulation and Coding techniques in a mobile network using Machine Learning to optimize capacity and coverage.
23EC4055		4	Analyze channel equalizers for enhancing efficiency in a mobile network using deep learning algorithms.
		6	Analyze mobile network optimization techniques using Machine Learning and Deep Learning algorithms.
		7	Evaluate the Machine Learning and Deep Learning algorithms for 5G and 6G mobile networks optimization
23EC3051	Advanced Embedded	1	Understand the concept of embedded systems and multicore System on chip.
		2	Identify the various communication interfaces and protocols for efficient embedded system and the interconnection networks.
		3	Development of Software Tools and Debugging Techniques
	Systems	4	Apply the concept of multicore SoC in building real time applications
		5	Analyse the programming of microcontroller and interface various peripheral devices to the microcontroller
		6	Analyse the simulation of microcontroller using simulation tools like Keil and Proteus
23EC3052	Embedded Systems for IoT	1	Able to Understand the requirements of functional blocks and the functioning of IoT devices



		2	Able to understand and apply the Communication models that are used for the development of the IoT based Systems
		3	Able to understand and apply different networking topologies and protocols used for the development of IoT based Networks
		4	Able to Understand and apply IoT Application in different Case studies
		5	Analyze the programming & interfacing of NODE MCU using the hardware/software tool
		1	Apply the different task-scheduling algorithms for real-time systems application
		2	Apply Multiprocessor scheduling and real-time communication, databases, and synchronization in Real-time System
	Real-time Embedded systems	3	Able to analyse an RTOS and be able to interpret the feasibility of a task set to accomplish and Timers.
23EC3053		4	Analyze to develop model-driven development approaches to construct an execution environment with case studies.
		5	Analyze a performance of real-time application and different task scheduling algorithms in real- time systems
		6	Analyze to develop a real-time application and different task-scheduling algorithms in real-time systems
	Cloud and Edge Computing	1	Able to understand the need for new computing paradigms and apply the major components of Cloud architectures.
		2	Able to Identify potential technical challenges of the transition process and suggest solutions.
23EC3054		3	Able to Build data collection, analytics, and decision-making capabilities into these Cloud and Edge compute systems, Analyze data and application requirements and pertaining issues.
		4	Able to Design and model infrastructures and analytics into Cloud and Edge Computing to perform decision-making.
		5	Design Cloud and Edge compute systems to provide multi-level intelligence for IoT, transducers and other devices, using the Open Fog Reference Architecture.
FC-1	Embedded System Design	1	Able to apply the principal concept of embedded systems and the architecture of embedded system design.



		2	Able to apply the role of controller, timer, and interfaces for embedded system design
		3	Able to design and analyse the various communication interface and protocols for efficient embedded systems
		4	Able to analyse an embedded system considering the trade-off between designing functionality in hardware versus software.
		5	Able to apply and analyse the Embedded system design knowledge using the architecture and programming and Performance analysis for modular implementation for a complete system.
		1	Able to Understand the various theoretical concepts related to wireless sensors and networking of the sensors
	Wireless sensor Networks	2	Apply WSNs Architectures, Energy consumption of Sensor nodes for the development of the IoT based Systems
22CPS3506		3	Apply different MAC protocols, Routing mechanism used for the development of WSNs Application
		4	Apply node and network management related concepts for real time application of WSNs
		5	Analyse the programming & interfacing of WSNs using the hardware/software tool
23MT2007	Random Variables and Stochastic Process	1	Apply Mathematical models of random phenomena and solve probabilistic problems.
		2	Analyze different types of random variables and compute statistical parameters of the random variables.
		3	Apply random processes in the time domain and model time varying linear systems.
		4	Analyze random processes in frequency domains and model spectral characteristics of LTI systems.
23EC2224F	Deep Network Architectures	1	Apply CNN and asses various metrics for realistic applications
		2	Apply various deep learning techniques for training and testing of data sets
		3	Apply various network architectures for the analysis of data
		4	Apply deep and recurrent neural networks with various case studies.
22IMP3101 R	Natural Language Processing and Applications	1	Apply the fundamental concepts in NLP and review different NLP applications.
		2	Apply the basic structure of NLP Pipelines for text-based applications.



		3	Analyze the performance of algorithms for semantics in NLP and prioritize them for the existing applications.
		4	Apply machine learning models for finding solutions for problems in NLP and judge their performance.
		5	Evaluate and Analyze the operations applied in NLP pipelines through Python code development using NLTK, SpaCY, and Tensorflow Frameworks.
		1	Understand the Foundation
		2	Interpret Qubits and Quantum Model of Computation
22IMP3506	Quantum computing	3	Presenting Quantum Algorithms – I
		4	Explain Quantum Algorithms – II
		5	Analyse quantum computing lab using matlab/Python
		1	Understand Data science, data collection, and data pre-processing
	Data visualization	2	Applying descriptive statistical sampling techniques to explore various real world data sets
22IMP3404		3	Build data wrangling models with data science libraries like NumPy and Pandas
		4	Applying various data visualization tools to explore the data
		5	Analyse data streams using visualisation techniques
	Data Engineering	1	Describe the fundamental concepts of DE and review different DE tools and applications.
		2	Illustrate and summarize the basic structure of data Pipelines.
22IMP3202		3	Analyze the performance of algorithms for building a 311 data pipeline and prioritize them for the existing applications.
		4	Apply Data pipelines for deployment in production using Apache Sparak and PySpark and judge their performance.
		5	Implement Data processing algorithms and Information retrieval techniques on standard database systems concepts using python.
		1	Understand the Basic concepts related to Biomedical signals and images
22IMP3303 R	Bio Medical Signal and Image Analysis	2	Understand the Bio medical signal processing methods to eliminate the artefacts arise in biomedical signals
		3	Understand the Biomedical imaging and enhancement techniques

		4	Apply signal processing approaches for biomedical signals and images
		5	Apply biomedical signal and image processing
		6	Analyse advanced signal processing approaches
		7	Analyze biomedical signals using recurrent deep learning networks and time-frequency analysis.
		1	Understand the fundamental concepts of a digital image processing system and transformation techniques
OEEC0011	Image Processing	2	Understand image enhancement techniques in spatial and frequency domains.
		3	Apply image restoration and compression techniques
		4	Apply image segmentation, representations, and description
		1	Understand machine learning concepts
05500017	Machine Learning for Engineering and Scientific applications	2	Apply machine learning techniques to engineering problems
OEEC0017		3	Explore real-world engineering and scientific applications
		4	Evaluate and interpret machine learning results
	Fundamentals of Robotics	1	Apply the functional elements to build simple robot
		2	Apply Denavit -Hattenberg parameters to position the manipulators
23EC2223R		3	Apply the differential motion through Jacobian to control the manipulator
		4	Analyze the force control techniques using Lagrange dynamic model
		5	Analyze the movement of manipulator with the required kinematics.
	Electronics Instruments & Automation	1	To understand the characteristics of Electronics instruments and their Measurements and use them to compute measurements.
23EC2231F		2	Explore the fundamental design concepts of Electronic Measuring Instruments and discover their usage in real time environment.
		3	Applying the importance of Control Systems in Automation to construct a robotic system with desired response.
		4	To analyze the industrial automation-based applications and summarize their advantages in sustainable development.
		5	Synthesize various electronic instruments and control systems for automation.



		1	Apply the control techniques for path planning.
		2	Apply the basics of DH parameters for developing
			the models of Advanced Robotic Manipulator.
			Apply the functional and critical operational
		3	Robotics methods for preparing advanced level of
23P A N330			Robotics.
23RAN330 4R	Advanced Robotics		Analyze the concepts of Advanced Robotics
		4	Systems and Real-time environment for various
			applications.
		5	Analyze the fetch and frieght robots with various
			coordinate frames and joint angles
		6	Analyze the kinematics and dynamics
		1	requirements using VREP robotic simulation tool
		1	Apply the control techniques for path planning.
		2	Apply the basics of DH parameters for developing
			Apply the functional and critical operational
		3	Apply the functional and critical operational Robotics methods for preparing advanced level of
		5	Robotics
			Analyze the concepts of Advanced Robotics
23RAN330	Advanced Robotics	4	Systems and Real-time environment for various
4A	A divalleed Roboties		applications.
		5	Analyze the fetch and frieght robots with various
			coordinate frames and joint angles
		6	Analyze the kinematics and dynamics
			requirements using VREP robotic simulation tool
		7	Analyze the construction and various parameters
		/	of a robot using the Studica Robotic System kit
	Advanced Robotics	1	Apply the control techniques for path planning.
		2	Apply the basics of DH parameters for developing
			the models of Advanced Robotic Manipulator.
		3	Apply the functional and critical operational
			Robotics methods for preparing advanced level of
			Robotics.
23RAN330		4	Systems and Real time environment for various
4P		4	applications
			Analyze the fetch and frieght robots with various
		5	coordinate frames and joint angles
			Analyze the kinematics and dynamics
		6	requirements using VREP robotic simulation tool
		7	Analyze the construction and various parameters
			of a robot using the Studica Robotic System kit
22D A NI220	Autonomous Vehicles & Automotive Electronics	1	Apply the functional elements of robotics to build
23RAN320 2		1	simple robot.
		2	Apply Denavit -Hattenberg parameters to position



			the manipulators
		2	Apply the differential motion through Jacobian to
		3	control the manipulator
		4	Analyse the force control techniques using
		4	Lagrange dynamic model
			Apply the basic mechanical and electrical systems
		1	concerning robots' locomotion and manipulation
			Apply the mathematical models and computational
		2	and motion control methods to mobile robotic
			systems
			Apply the sensor systems related to state
23RAN310	AUTONOMOUS MOBILE	3	measurements, navigation and localization
2R	ROBOT SYSTEMS		Analyse the A stor Diikstre algorithm for
		4	Analyse the A-star, Dijkstra algorithin for
		5	planning the required path.
		3	Analyse the path planning for the multiple robots
		-	Analyze different aspects of stability for a given
		6	robot model and apply the mathematical model for
			the desired movements
		1	Apply the basic mechanical and electrical systems
			concerning robots' locomotion and manipulation.
			Apply the mathematical models and computational
		2	and motion control methods to mobile robotic
	AUTONOMOUS MOBILE ROBOT SYSTEMS		systems.
23RAN310 2A		3	Apply the sensor systems related to state
			measurements, navigation, and localization.
		4	Analyse the A-star, Dijkstra algorithm for
			planning the required path.
		5	Analyse the path planning for the multiple robots
		6	Analyze different aspects of stability for a given
			robot model and apply the mathematical model for
			the desired movements
		7	Develop a proper mapping and path planning
			algorithm for the locomotion of a given robot.
			Apply the basic mechanical and electrical systems
		1	concerning robots' locomotion and manipulation
			Apply the mathematical models and computational
		2	and motion control methods to mobile robotic
23RAN310 2P		2	systems
			Apply the sensor systems related to state
	AUTONOMOUS MOBILE	3	measurements, navigation, and localization
	ROBOT SYSTEMS		Analysis the A stor Differen algorithm for
		4	Analyse the A-star, DIJKstra algorithm for planning the required path
		F	A notive the notion for the multiple set of
		3	Analyse the pain planning for the multiple robots
		6	Analyze different aspects of stability for a given
			robot model and apply the mathematical model for
			the desired movements



		7	Develop a proper mapping and path planning
		1	Apply Norman's model to HMI
		1	Apply Norman's model to Thin Apply different GOMS models. Fitts Laws for
		2	improving the Human Machine Interaction
23RAN340	Human Machine Interface		Apply the concepts of Brainwayes for Bain
6	& Brain Machine Interface	3	Machine Interface
			Analyze different methodologies for HMI/BMI
		4	Applications
			Apply the fundamental concepts of signal
		1	processing to computer vision
			Apply different methodologies of feature
		2	extraction pattern analysis and visual geometric
		-	modelling to stochastic optimization problems
		-	Apply various Boundary and Edge Detection
23RAN350	Computer Vision	3	techniques in 3D signal (Video).
7	& Robotics Applications		Analyze the classifiers in different applications
		Λ	such as Biometrics, Medical diagnosis, document
		4	processing, mining of visual content, surveillance,
			and advanced rendering.
			Analyse the histogram and texture of image and
		5	Classification Model LDA in Python / MATLAB
			for Computer Vision applications
		1	Understand the basic principles of robot trajectory
			planning
		2	Apply motion of robot in the presence of obstacles
		3	Analyze motion planning and robot control
23RAN310	Robot Motion Planning,	4	Perform basic motion, force, and hybrid motion-
1R	Dynamics& Control		force control to mobile robotics.
		5	Perform lab experiments using Robo studio and
		5	Move it studio for motion planning.
		6	Perform skill experiments using Move it studio for
		0	motion planning.
23RAN310 1A		1	Understand the basic principles of robot trajectory
			planning
		2	Apply motion of robot in the presence of obstacles
		3	Analyze motion planning and robot control
		4	Perform basic motion, force, and hybrid motion-
	Robot Motion Planning,		force control to mobile robotics.
	Dynamics& Control	5	Perform lab experiments using Robo studio and
			Movelt studio for motion planning.
		6	Perform skill experiments using Moveit studiofor
		7	motion planning.
			to be achieved by a robot
22D A N210	Pohot Motion Dianning	1	U be define veu by a 10001.
231AN310	KOUUL MUUUII Flaining,	1	Tonderstand the basic principles of robot trajectory



2         Apply motion of robot in the presence of obstacles           3         Analyze motion planning and robot control           4         Perform basic motion, force, and hybrid motion-force control to mobile robotics.           5         Perform lab experiments using Mobo studio and Movelt studio for motion planning.           6         Perform skill experiments using Moveit studiofor motion planning.           7         Develop algorithms for a predefined motion curve to be achieved by a robot.           7         Develop algorithms for a predefined motion curve to be achieved by a robot.           7         Develop algorithms for a predefined motion curve to be achieved by a robot.           8         Perform skill experiments using Moveit studiofor motion planning.           23RAN320         Robot Manipulation &         1           2         Apply the concept of forces/ friction to find out the performance of the manipulator           2         Apply the concept of fordback control and odometry for Mobile robots           4         Apply the concept of fedback control and odometry for Mobile robots           1         Understand the concept of fedback control and odometry for Mobile robots           2         Apply the concept of fedback control and odometry for Mobile robots           3         Apply the concept of fedback control and odometry for Mobile robots           4         Analyze A1 in Robotics Control	1P	Dynamics& Control		planning
23RAN320         3         Analyze motion planning and robot control           23RAN320         6         Perform hasic motion, force, and hybrid motion-force control to mobile robotics.           23RAN320         7         Develop algorithms for a predefined motion curve to be achieved by a robot.           23RAN320         7         Develop algorithms for a predefined motion curve to be achieved by a robot.           2         4         Apply the concept of forces/ friction to find out the performance of mobile robots.           3         4         Apply the concept of forces/ friction to find out the performance of mobile robots.           4         Apply the concept of forces/ friction to find out the performance of mobile robots.           4         Apply the concept of forces/ friction to find out the performance of mobile robots.           4         Apply the concept of forces/ friction to find out the performance of mobile robots.           4         Apply the concept of force/ friction to find out the performance of mobile robots.           5         1         Understand the concepts of Al           2         Apply the posic principles of Al in solutions that require planning.           4         Analyze Al in Robotics.         Apply the posic principles of taks.           2         Apply multi-agent systems, parallel, scalable, stable for different types of taks.         3           3         Apply multi-agent			2	Apply motion of robot in the presence of obstacles
23RAN320         Robot Manipulation & 3			3	Analyze motion planning and robot control
23RAN320     Robot Manipulation & 3 <sup>4</sup> <sup>6</sup> <sup>6</sup> <sup>7</sup> <sup>7</sup> <sup>6</sup> <sup>6</sup> <sup>7</sup> <sup>7</sup> <sup>7</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup> <sup>8</sup>			4	Perform basic motion, force, and hybrid motion-
23RAN320         Robot Manipulation & 3			4	force control to mobile robotics.
23RAN320     Robot Manipulation & 3 <sup>3</sup> Movelt studio for motion planning. Perform skill experiments using Moveit studiofor motion planning. Develop algorithms for a predefined motion curve to be achieved by a robot. Understand the various contacts elements required for robot's manipulator 2 Apply the concept of forces/ friction to find out the performance of the manipulator 3 Apply the basic concepts used to check the performance of mobile robots 4 Apply the basic principles of AI 2 Apply basic principles of AI apply basic principles of SN apply the Cooperative algorithms, earlier progress of swarm robotics algorithms, reatures of swarm         robotics algorithms, reatures of swarm         movements efficiently bigital Design & Computer Architecture attract the sequential and memory circuits using flip-flops advinting for avaigate and control swarm movements efficiently build the combinational and programmable digital         logic circuits using logic gates and optimization         methods advint the sequential			~	Perform lab experiments using Robo studio and
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23RAN320         Robot Manipulation & Wheeled Mobile Robots         1         Understand the various contacts elements required for robot's manipulator           2         Apply the concept of forces/ friction to find out the performance of the manipulator         3           3         Wheeled Mobile Robots         2         Apply the concept of feedback control and odometry for Mobile robots           4         Apply the concept of feedback control and odometry for Mobile robots         4         Apply the concept of feedback control and odometry for Mobile robots           22RAN340         Artificial Intelligence for Robotics         1         Understand the concepts of AI           2         Apply basic principles of AI in solutions that require problem-solving         3         Apply basic principles of AI in solutions that require planning           23RA51A4         Swarm Robotics Control Systems         1         Apply updictic for different types of tasks           23RA51A4         Digital Design & Computer Architecture         3         Apply updictic algorithms, peatilet, scalable, stable for different types of tasks           23EC1202         Digital Design & Computer Architecture         1         Build the combinational and programmable digital logic circuits using logic gates and optimization methods           2         Construct the sequential and memory circuits using flip-flops         3         Organization modules           3         Develop and analy			(	Perform skill experiments using Moveit studiofor
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23RAN320       Robot Manipulation &       2       the performance of the manipulator         3       Wheeled Mobile Robots       3       Apply the basic concepts used to check the performance of mobile robots         4       Apply the concept of feedback control and odometry for Mobile robots       4       Apply basic principles of AI         22RAN340       Artificial Intelligence for Robotics       1       Understand the concepts of AI in solutions that require problem-solving         3       Apply basic principles of AI in solutions that require problem-solving       3       Apply basic principles of AI in solutions that require problem-solving         3       Robotics       4       Analyze AI in Robotics       Apply basic principles of AI in solutions that require problem-solving         3       Swarm Robotics Control Systems       1       Apply basic principles of AI in solutions that require planning         4       Analyze AI in Robotics       Apply basic principles of AI in solutions that require problem-solvand variousSwamRoboticsControl olSystemsfordirection study       2         23RA51A4       Swarm Robotics Control       3       Apply concepts of Swam Robotics Control Systems and Creating Advanced behavior module.         23RA51A4       Digital Design & Computer Architecture       4       Apply the Cooperative algorithms, reatures of swarm robotics algorithms, Features of swarm robotics algorithms, Features of swarm robotics algorithms, features of swarm robotics alg			2	Apply the concept of forces/ friction to find out
3     Wheeled Mobile Robots     3     Apply the basic concepts used to check the performance of mobile robots       4     Apply the concept of feedback control and odometry for Mobile robots       22RAN340     Artificial Intelligence for Robotics     1     Understand the concepts of AI       2     Apply basic principles of AI in solutions that require planning     4     Analyze AI in Robotics       3     Apply the principles of AI in solutions that require planning     4     Analyze AI in Robotics       4     Analyze AI in Robotics     1     Apply the concepts of the solutions that require planning       4     Analyze AI in Robotics     1     Apply the solutions that require planning       4     Analyze AI in Robotics     2     Apply the concepts of Swam Robotics Control olSystems of different types of tasks       3     Apply concepts of Swam Robotics Control Systems     3     Apply the Cooperative algorithms, earlier progress of swarm robotics algorithms, reatures of swarm robotics algorithms, reatures of swarm robotics algorithms, features of swarm robotics algorithms for navigate and control swarm movements efficiently       23EC1202     Digital Design & Computer Architecture     1     Build the combinational and programmable digital logic circuits using logic gates and optimization methods       23EC1202     Digital Design & Computer Architecture     3     Organize computer architecture and instructions sequence       4     Digital Design & Computer Architecture	23RAN320	Robot Manipulation &	Δ	the performance of the manipulator
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23RA51A4       Swarm Robotics Control       4       Analyze AI in Robotics         23RA51A4       Swarm Robotics Control       1       ApplytheprinciplesandvariousSwamRoboticsControl         23RA51A4       Swarm Robotics Control       2       Apply multi-agent systems, parallel, scalable, stable for different types of tasks         23RA51A4       Swarm Robotics Control       3       Apply multi-agent systems, parallel, scalable, stable for different types of tasks         2       Apply multi-agent systems, parallel, scalable, stable for different types of tasks       3         3       Apply concepts of Swarm Robotics Control Systems and Creating Advanced behavior module.         4       Apply the Cooperative algorithms, earlier progress of swarm robotics algorithm for navigate and control swarm movements efficiently         23EC1202       Digital Design & Computer Architecture       1       Build the combinational and programmable digital logic circuits using logic gates and optimization methods         23EC1202       Digital Design & Computer Architecture       3       Construct the sequential and memory circuits using flip-flops         23EC1202       Digital Design & Computer Architecture       3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O       Organization modules       Develop and analyze of computer architecture	5		3	Apply basic principles of AI in solutions that
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23RA51A4       Swarm Robotics Control       1       ApplytheprinciplesandvariousSwamRoboticsControl         23RA51A4       Swarm Robotics Control       2       Apply multi-agent systems, parallel, scalable, stable for different types of tasks         23RA51A4       Swarm Robotics Control       3       Apply concepts of Swam Robotics Control         Systems       3       Apply concepts of Swam Robotics Control       Systems and Creating Advanced behavior module.         4       4       Apply the Cooperative algorithms, earlier progress of swarm robotics algorithm for navigate and control swarm movements efficiently         23EC1202       Digital Design & Computer Architecture       1       Build the combinational and programmable digital logic circuits using logic gates and optimization methods         23EC1202       Digital Design & Computer Architecture       2       Construct the sequential and memory circuits using flip-flops         23EC1202       Digital Design & Computer Architecture       3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O       Organization modules       Develop and analyze of computer architecture			4	Analyze AI in Robotics
23RA51A4       Swarm Robotics Control       2       Apply multi-agent systems, parallel, scalable, stable for different types of tasks         23RA51A4       Swarm Robotics Control Systems       3       Apply concepts of Swarm Robotics Control Systems and Creating Advanced behavior module.         4       4       Apply the Cooperative algorithms, earlier progress of swarm robotics algorithms, Features of swarm robotics algorithm for navigate and control swarm movements efficiently         23EC1202       Digital Design & Computer Architecture       1       Build the combinational and programmable digital logic circuits using logic gates and optimization methods         23EC1202       Digital Design & Computer Architecture       3       Organize computer architecture and instructions sequence         4       6       0       Organization modules       0         5       Develop and analyze of computer architecture modules using basic combinational sequential and the sequence			1 2	ApplytheprinciplesandvariousSwamRoboticsContr
23RA51A4       Swarm Robotics Control Systems       2       Apply multi-agent systems, parallel, scalable, stable for different types of tasks         3       Apply concepts of Swam Robotics Control Systems and Creating Advanced behavior module.         4       Apply the Cooperative algorithms, earlier progress of swarm robotics algorithm for navigate and control swarm movements efficiently         23EC1202       Digital Design & Computer Architecture       1         2       Construct the sequential and memory circuits using flip-flops         3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and		Swarm Robotics Control Systems		olSystemsfordirection study
23RA51A4       Swarm Robotics Control Systems       3       Stable for different types of tasks         3       Apply concepts of Swam Robotics Control Systems and Creating Advanced behavior module.         4       Apply the Cooperative algorithms, earlier progress of swarm robotics algorithms, Features of swarm robotics algorithm for navigate and control swarm movements efficiently         23EC1202       Digital Design & Computer Architecture       1       Build the combinational and programmable digital logic circuits using logic gates and optimization methods         2       Construct the sequential and memory circuits using flip-flops       3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules       5       Develop and analyze of computer architecture modules using basic computer architecture				Apply multi-agent systems, parallel, scalable,
23RA51A4       Swarm Robotics Control Systems       3       Apply concepts of Swam Robotics Control Systems and Creating Advanced behavior module.         4       Apply the Cooperative algorithms, earlier progress of swarm robotics algorithm for navigate and control swarm movements efficiently         23EC1202       Digital Design & Computer Architecture       1         23EC1202       Digital Design & Computer Architecture       2         Construct the sequential and memory circuits using flip-flops       3         3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and				stable for different types of tasks
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23EC1202Digital Design & Computer ArchitectureAApply the Cooperative algorithms, earlier progress of swarm robotics algorithms, Features of swarm robotics algorithm for navigate and control swarm movements efficiently23EC1202Digital Design & Computer Architecture1Build the combinational and programmable digital logic circuits using logic gates and optimization methods23EC1202Digital Design & Computer Architecture2Construct the sequential and memory circuits using flip-flops3Organize computer architecture and instructions sequence3Organize computer architecture and I/O Organization modules5Develop and analyze of computer architecture modules using basic combinational sequential and				Systems and Creating Advanced behavior module.
23EC1202       Digital Design & Computer Architecture       4       of swarm robotics algorithms, Features of swarm robotics algorithms, Features of swarm movements efficiently         23EC1202       Digital Design & Computer Architecture       1       Build the combinational and programmable digital logic circuits using logic gates and optimization methods         2       Construct the sequential and memory circuits using flip-flops       3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules       5       Develop and analyze of computer architecture modules using basic combinational sequential and sequentis and sequential an			4	Apply the Cooperative algorithms, earlier progress
23EC1202       Digital Design & Computer Architecture       2       Build the combinational and programmable digital logic circuits using logic gates and optimization methods         2       Construct the sequential and memory circuits using flip-flops         3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and				of swarm robotics algorithms, Features of swarm
23EC1202       Digital Design & Computer Architecture       1       Build the combinational and programmable digital logic circuits using logic gates and optimization methods         2       Construct the sequential and memory circuits using flip-flops         3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and				robotics algorithm for navigate and control swarm
23EC1202 Digital Design & Computer Architecture Architecture 4 $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				movements efficiently
23EC1202       Digital Design & Computer Architecture       1       logic circuits using logic gates and optimization methods         2       Construct the sequential and memory circuits using flip-flops         3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and			1	Build the combinational and programmable digital
23EC1202       Digital Design & Computer Architecture       2       Construct the sequential and memory circuits using flip-flops         3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and	23EC1202		1	logic circuits using logic gates and optimization
23EC1202       Digital Design & Computer Architecture       2       Construct the sequential and memory circuits using flip-flops         3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and				Construct the construction of the construction
23EC1202       Digital Design & Computer Architecture       3       Organize computer architecture and instructions sequence         4       Model the Memory Architecture and I/O Organization modules         5       Develop and analyze of computer architecture modules using basic combinational sequential and		Digital Design & Computer Architecture	2	Construct the sequential and memory circuits
Architecture Archi				Using http://ops
4     Model the Memory Architecture and I/O       0rganization modules       5     Develop and analyze of computer architecture       modules using basic combinational sequential and			3	organize computer architecture and instructions
4 Organization modules 5 Develop and analyze of computer architecture modules using basic combinational sequential and				Model the Memory Architecture and I/O
5 Develop and analyze of computer architecture modules using basic combinational sequential and			4	Organization modules
5 modules using basic combinational sequential and				Develop and analyze of computer architecture
			5	modules using basic combinational sequential and



			memory logics
23EC1203	Basic Electrical &	1	Understand the basic concepts of circuits and its fundamentals
		2	Grasp the principles of AC circuits, including sinusoidal waveforms, impedance, and power factor.
	Electronic Circuits	3	Comprehend the behavior of basic electronic components, such as diodes, and transistors.
		4	Understand the basic functional Principles of analog and digital ICs.
		1	Apply the knowledge of Semiconductor physics and discuss BJT configurations and their applications
		2	Apply the limitations of BJT and discuss the characteristics and applications of Field Effect Transistors
23EC2104R	Analog Electronic Circuit Design	3	Apply the linear and nonlinear circuits approaches and realize the characteristics of operational Amplifiers
		4	Apply the concept of a feedback system and realize the working principles of Oscillators and multivibrators
		5	Design and analyze analog circuits for real-time applications using Passive and Active Components.
		6	Simulate and analyze electronic circuits using Multisim and myDAQ.
23EC2104A /P	Analog Electronic Circuit Design	1	Apply the knowledge of Semiconductor physics and discuss BJT configurations and their applications
		2	Apply the limitations of BJT and discuss the characteristics and applications of Field Effect Transistors
		3	Apply the linear and nonlinear circuits approaches and realize the characteristics of operational Amplifiers
		4	Apply the concept of a feedback system and realize the working principles of Oscillators and multivibrators
		5	Design and analyze analog circuits for real-time applications using Passive and Active Components.
		6	Simulate and analyze electronic circuits using Multisim and myDAQ.
23EC2211R	VLSI Design	1	Realize MOS device with transient and DC characteristics



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		2	Understand the characteristics of CMOS inverter
		3	Analyze the static and dynamic characteristics of
			CMOS circuits
		4	Evaluate the performance of CMOS circuits
			Design and implement the combinational and
		5	sequential circuits using Cadence VLSI Design
			Full Suite
		6	Design and analysis of VLSI circuits for real time
		0	applications.
		1	Realize MOS device with transient and DC
		1	characteristics
		2	Understand the characteristics of CMOS inverter
	VLSI Design	3	Analyze the static and dynamic characteristics of
22EC2211A			CMOS circuits
23EC2211A /D		4	Evaluate the performance of CMOS circuits
/1		5	Design and implement the combinational and
			sequential circuits using Cadence VLSI Design
			Full Suite
		6	Design and analysis of VLSI circuits for real time
			applications.
	Digital VLSI Design	1	Realize Digital CMOS device with different
			methodologies
		2	Understand the various CAD Tool design
23EL3001R		Δ	synthesis and functional simulation processes
		2	Design various combinational and sequential
		5	digital circuits using Verilog HDL.
		4	Design and modeling of various CMOS digital
			circuits.
		5	Design, implement, and analyze the combinational
			and sequential circuits using Xilinx Vivado Full
			Suite

Academic Professor I/C

HOD-ECE